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A REPAIRABLE ITEM INVENTORY MODEL

PHILLIP FREEMAN MCNALL
AND
JOHN WAYNE HATCHETT

REMARKS
NAVAL POSTGRADUATE SCHOOL
PACIFIC GROVE, CALIF. 93940

A REPAIRABLE ITEM INVENTORY MODEL

by

Phillip Freeman McNall
Lieutenant Commander, Supply Corps, United States Navy
B.S., United States Naval Academy, 1958

and

John Wayne Hatchett
Lieutenant, Supply Corps, United States Navy
B.S., United States Naval Academy, 1958


Submitted in partial fulfillment

for the degree of

MASTER OF SCIENCE IN OPERATIONS RESEARCH

from the

UNITED STATES NAVAL POSTGRADUATE SCHOOL
October 1966



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ABSTRACT

The purpose of this thesis is to structure a model for an inventory system carrying items that are issued to fill customer demands, are repaired by the system after use, wearout, or failure and then are subsequently reissued. This system is called a repairable item inventory system. Since all used items are not economically repairable, new items must be procured from time to time to maintain the system. The deterministic model adopted treats the repair and procurement problems simultaneously and develops inventory decision rules for repairable items.

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TABLE OF SYMBOLS AND ABBREVIATIONS

| | |
|------------|---|
| A_1 | Fixed cost to place a procurement order |
| A_2 | Fixed cost to place a repair order |
| ADP | Automatic data processing |
| ASO | Aviation Supply Office, Philadelphia, Pa. |
| AUTODIN | Automatic digital network |
| C_1 | Unit cost of a new item |
| C_2 | Unit cost of repair |
| D | Demand rate |
| Δ_a | The number of units of time after the beginning of a procurement cycle for placing a procurement order. |
| h_1 | Holding cost for RFI material (\$/unit-yr) |
| h_2 | Holding cost for NRFI material (\$/unit-yr) |
| ICP | Inventory control point |
| n | $\frac{T_1}{T_2}$, the number of repair cycles in a procurement cycle. |
| NRFI | Non-ready-for-issue |
| O&R | Overhaul and repair activity |
| Q_1 | Procurement quantity |
| Q_2 | Repair quantity |
| Q_1^* | Optimal procurement quantity |
| Q_2^* | Optimal repair quantity |
| r_0 | Field recovery rate |
| r_2 | Repair recovery rate |
| R | $1 - r_0 r_2$ |
| RFI | Ready-for-issue |
| T_1 | Procurement cycle |

| | |
|----------|---------------------------|
| T_2 | Repair cycle |
| τ_1 | Procurement leadtime |
| τ_2 | Repair leadtime |
| x_1 | Procurement reorder point |
| x_2 | Repair reorder point |

DEFINITIONS OF TERMS

| | |
|-------------------------------------|---|
| Consumable | An item that is either consumed in use or discarded after wearout or failure. |
| Field recovery rate | Percent of items issued that are subsequently returned to the overhaul and repair activity. |
| Holding costs | The costs associated with the physical maintenance of an inventory. |
| Information and Issue systems costs | The costs associated with operating an inventory system excluding procurement, repair and holding costs. |
| Inventory control point | An inventory manager in the United States Naval Supply System (for example ASO). |
| Inventory Manager | An activity responsible for the procurement and inventory control of items in an inventory system. |
| Non-ready-for-issue | Condition of an item that is not capable of providing complete flow of services in its designed use. |
| Operating doctrine | A set of rules which prescribe procurement and repair quantities and respective reorder points (when and how much to procure and repair). |
| Overhaul and Repair activity | An industrial activity responsible for testing, checking, repairing, etc. components and equipments designated as repairable by the inventory manager on either a scheduled or emergency basis. |
| Overhaul and Repair recovery rate | Percent of items returned to the overhaul and repair activity that are subsequently returned in an RFI condition to the stock point. |
| Procurement costs | The costs associated with placing a procurement order including the cost of the items. |
| Procurement cycle | Time between arrival of successive procurement quantities. |
| Procurement leadtime | Time between the placement of a procurement order and receipt of the procurement quantity. |
| Ready-for-issue | Condition of an item that is capable of providing complete flow of services in its designed use. |

| | |
|-----------------|---|
| Repairable | An item that can be repaired after wearout or failure and subsequently provide some flow of services. |
| Repair costs | The costs associated with placing a repair induction including the cost of repairing the items. |
| Repair cycle | Time between arrival of successive repair quantities. |
| Repair leadtime | Time between the placement of an induction order and receipt of the repair quantity. |
| Shortage costs | The cost incurred by the system when a demand cannot be filled from stock. |
| Stock point | An activity responsible to the inventory manager for the receipt, storage and issue of material and the report of transactions. |

I. Introduction

Inventories of physical goods can be found in every sector of the economy. These inventories exist primarily to make goods available to customers or producers without delay and to increase sales and profits. For example, an industrial concern must have raw materials and finished products on hand to avoid delay in production and to respond quickly to customer demands for a variety of finished products; a supermarket carries perishable fruits and vegetables because few customers are willing to wait for their demands to be filled from a truck farm; a retail clothing store must have a variety of items to display in order to attract customers. Although no profit motive exists, military inventory systems carry a diversity of goods in order to satisfy the demands of fleet units without production and transportation delays.

Since inventories exist, it is natural to try to classify the types of items carried. Some of the adjectives commonly used to describe goods are perishable, raw, durable, finished, hard, soft, technical, and general. Obviously a given item might be described by one or more of these terms. However, two broad classifications, namely, consumable and repairable, characterize any item. A consumable item is one that is either consumed in use or discarded after wear out or failure. Examples of consumable items are paper, pencils, paint, fuel, nails, food, gaskets, resistors, and razor blades, to mention only a few. In general, a repairable item is one that can be repaired after failure or wear out and subsequently will provide some flow of services to the user. Automobiles, aircraft, refrigerators, radios, engines, and hydraulic pumps are all examples of repairable items. They can be repaired by the owner or user, a local repair shop, or the manufacturer. In more general terms the

level of repair can be classified as local, intermediate, or major. An analogy in the military is respectively, ship, tender, and shipyard.

A more specific definition of a repairable is an item that is returned to a major repair point after use, overhauled or repaired, put back on the shelf in a ready-for-issue (RFI) condition, and reissued to a customer to satisfy a demand. This definition will apply throughout this paper and can be construed as a military application of the term repairable.

Consumable and repairable item inventories in the United States are worth billions of dollars and are costly to manage. Therefore, once the type of inventory has been established, an effective system to maintain and control the inventory should be developed. In private and commercial concerns, effective control of inventories can result in decreased costs, increased sales and profits and customer satisfaction. In the military, prudent management of inventories may contribute to increased weapons system effectiveness, decreased inventory investment and decreased system costs.

In any system carrying consumable items a set of rules to determine how much of an item to buy and when to buy i.e., an operating doctrine, must be established. In a repairable system the procurement decision is augmented by an additional decision of how much and when to repair. Thus, the additional repair decision is the basic difference between a consumable and a repairable item inventory system.

Typically, existing inventory control models have applied only to consumable items. "Optimal" order equations resulting from consumable model development have been implemented successfully by both the military and industrial concerns. Although increased management attention has been

focused on repairables over the past ten years, repairable inventory decisions have been largely based upon experience and intuition. Therefore, the purpose of this thesis is to investigate the repairable item inventory problem and to develop decision rules for a repairable inventory model giving due consideration to the costs associated with a repairable system.

It should be mentioned at this point that the decision to designate an item as repairable or consumable is not perfunctory. A decision to repair or discard occurs not only in the intermediate step when an item is provisioned for a system, but also in the initial or design stage and finally in the repair or overhaul stage. The most critical stage for an inventory system is initial provisioning. What criteria should be used to designate an item (already in the production phase) as repairable or consumable? What level of repair should be designated? No specific criteria have been developed to answer these questions so far as the authors can determine, and it is not the purpose of this paper to do so. However, it should be noted that the rationale behind designating an item as a repairable is that it is more economical to repair than to discard. Basically then, this decision involves the trade-off between costs of repair versus discard.

2. An Existing Repairable Inventory System

To better understand how a repairable system operates, the writers examined the Naval Aviation Supply System. This system exists to support 8,300 aircraft in the Navy. The inventory consists of 393,000 line items valued at 2.1 billion dollars. Of these line items, 31,000 are designated as repairable and these items account for 56% of the inventory value.¹ The inventory manager responsible for procurement and inventory control of all aviation items is the Naval Aviation Supply Office (ASO) located in Philadelphia, Pennsylvania. The items are stored in and issued from a network of stockpoints located throughout the Naval Supply System (e.g. Alameda, Norfolk, San Diego, and Yokosuka, Japan). Additionally there are seven major repair points called overhaul and repair activities (O&R) located in the United States. A fourth component, Air Systems Command (a Navy Bureau), provides technical direction and budget policy to ASO and also administers the seven O&R activities located at various air stations throughout the system.

If an item fails or is demolished in the field, a replacement is made from existing stock. The carcass (if suitable) is then considered a non-ready-for-issue (NRFI) item and is sent to an O&R (through a stockpoint) for repair.

Since the seven O&R activities are each juxtaposed to a reporting stockpoint, the latter actually receives and accounts for the NRFI item. This receipt is reported to the inventory manager (ASO) via rapid data transmission facilities. In this sense, the stock points are called reporting activities, i.e. all inventory transactions are reported to ASO who is in turn responsible for inventory control. When ASO determines

¹ASO Management Resumé - Second Quarter Fiscal Year 1966.

that an item should be repaired to meet expected demand or to meet existing backorders, an O&R activity is directed to induct the NRFI item(s). Induction scheduling between ASO and the O&R occurs on a weekly basis through a computerized scheduling system. Under present circumstances, most of the items inducted have backorders outstanding. This situation eliminates batching of NRFI items to a great extent. Once the item is repaired, it is returned to the stock point in RFI condition and subsequently issued to meet demand or fill backorders. The system is depicted in Figure 1.

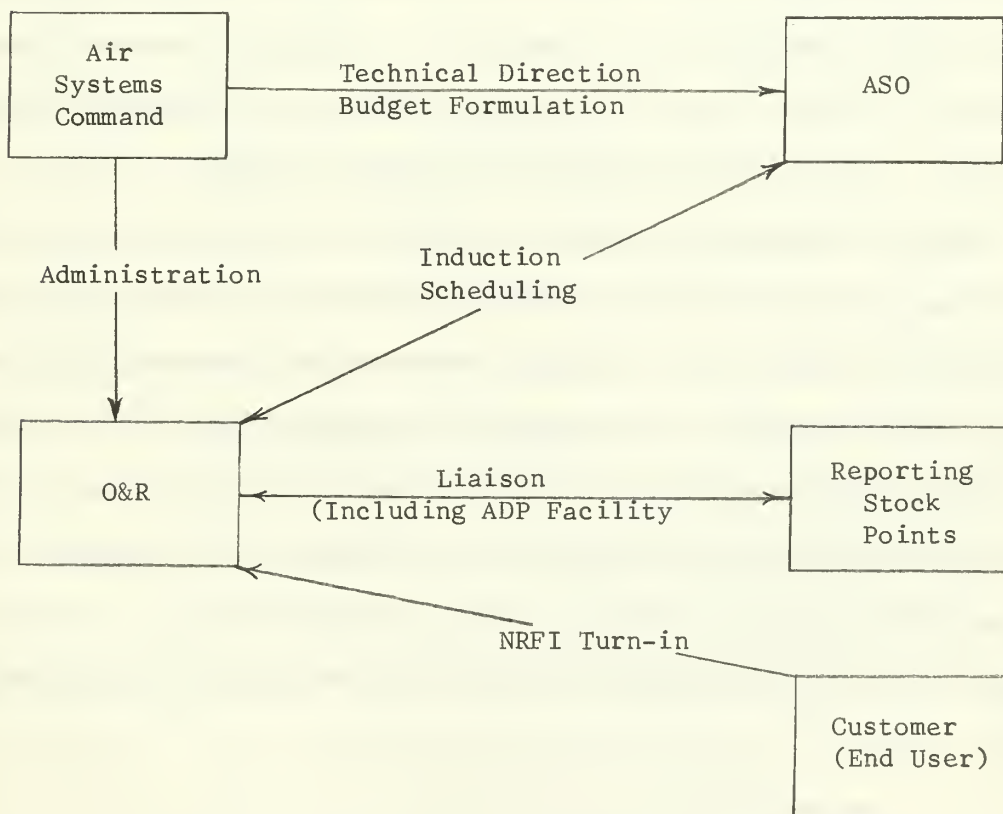


Figure 1. Naval Aviation Supply System (Repairable Items)

3. A Repairable Model

3.1. Model Description

Inventory systems such as the one just described can be classified rather broadly as multiechelon with repair. Analytical studies of multiechelon systems have shown the computations to be such that either simplifying assumptions or approximations are necessary. The introduction of the repair aspect into the system certainly complicates any attempt at model structuring even at single echelon levels. It was felt that simplifying assumptions would lead to results more in keeping with the objective of this thesis. Also a search of the literature has revealed that very little work has been done in model structuring for the repair inventory system of the type discussed in Section 2. The model presented here is intended to provide a basis for future studies and represents an initial attempt to structure a model for the repairable system.

Suppose a repairable system, consisting of one inventory control-point (ICP), one stock point and one overhaul and repair activity, controls the inventory of a single item. Demands from various customers are placed only at the stock point. The system has continuous updating of records, i.e., transaction reporting. When items wear out or fail, the customer can either scrap the item or return it to the O&R. After inspection the O&R can either scrap the item or repair and return it to the system. Both ready-for-issue and not-ready-for-issue flow of material is depicted in Figure 2.

3.2. Assumptions

Assume that the annual demand rate (D) is known and constant over time. To reiterate, the basic management decisions to be made are when and how much to procure and when and how much to repair. In this model

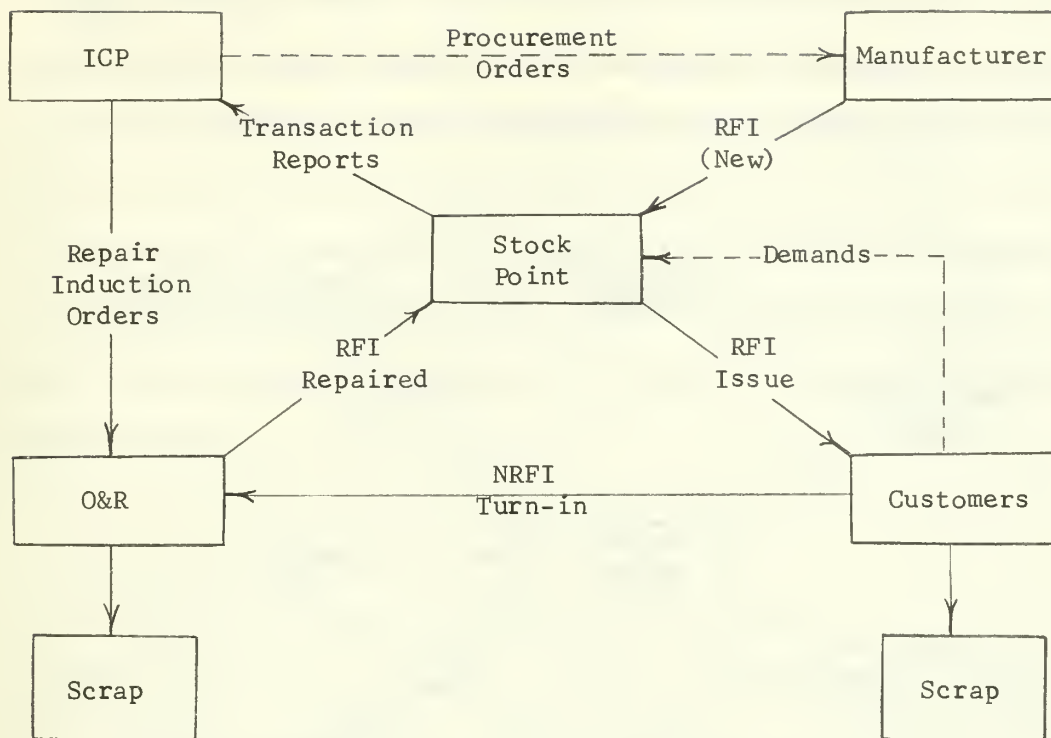


Figure 2. Material Flow in a Repairable System

procurement of new items serves to replace items lost by attrition. Suppose that both procurement lead time (\mathcal{T}_1) and repair lead time (\mathcal{T}_2) are known constants independent of the quantity ordered, the quantity inducted for repair, and the annual demand. Furthermore, the rate at which NRFI items are returned to the O&R, called field recovery rate (r_0), and the rate at which the O&R returns RFI to the stockpoint, called O&R recovery rate (r_2), are considered to be known. Items are always procured and repaired in lot sizes, Q_1 and Q_2 respectively, with no price breaks or split deliveries. For the sake of definiteness suppose the system operates indefinitely with the item never becoming obsolete.

The question of when to induct material into the repair operation is partially answered with the assumption that an induction is made whenever a predetermined number of NRFI items have accumulated. In order to return

a lot size Q_2 to the stockpoint it is necessary to induct an amount $\frac{Q_2}{r_2}$. This assumption reduces the problem to one of determining Q_2 . A more complete pictorial representation of the system is seen in Figure 3.

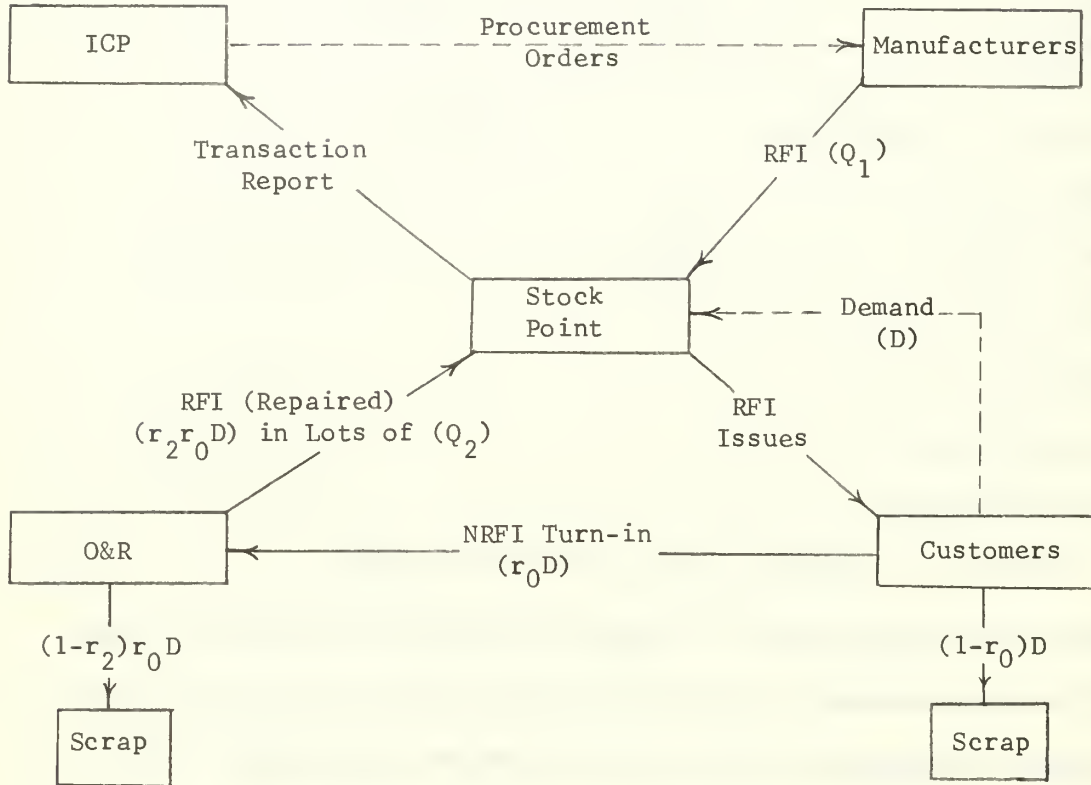


Figure 3. Repair System with Assumptions

Under the assumptions of deterministic demand and lead times, it is not necessary to maintain a safety stock. We will require then that whenever the RFI inventory reaches zero, a procurement quantity of size Q_1 will arrive. Thus, the system is never out of stock. Between procurement arrivals, depleting RFI stock is replenished with repaired items.¹ Also, a repetitive system will be established regardless of the initial provis-

¹Under these assumptions it is possible, though extremely unlikely, for a procurement quantity, Q_1 , and a repair quantity, Q_2 , to arrive at exactly the same instant of time. Accordingly it will be assumed that this case does not arise.

ioning policy, so that it is sufficient to analyze only one cycle to determine system characteristics. Further, it is advantageous to define a cycle as the length of time between the arrival of two successive procurements. This cycle will be called the procurement cycle and is denoted T_1 . A repair cycle, denoted T_2 , is defined to be the time between arrival of successive RFI repair quantities. Figure 4 depicts a typical procurement and repair cycle and illustrates the relationship between the RFI and NRFI inventory.

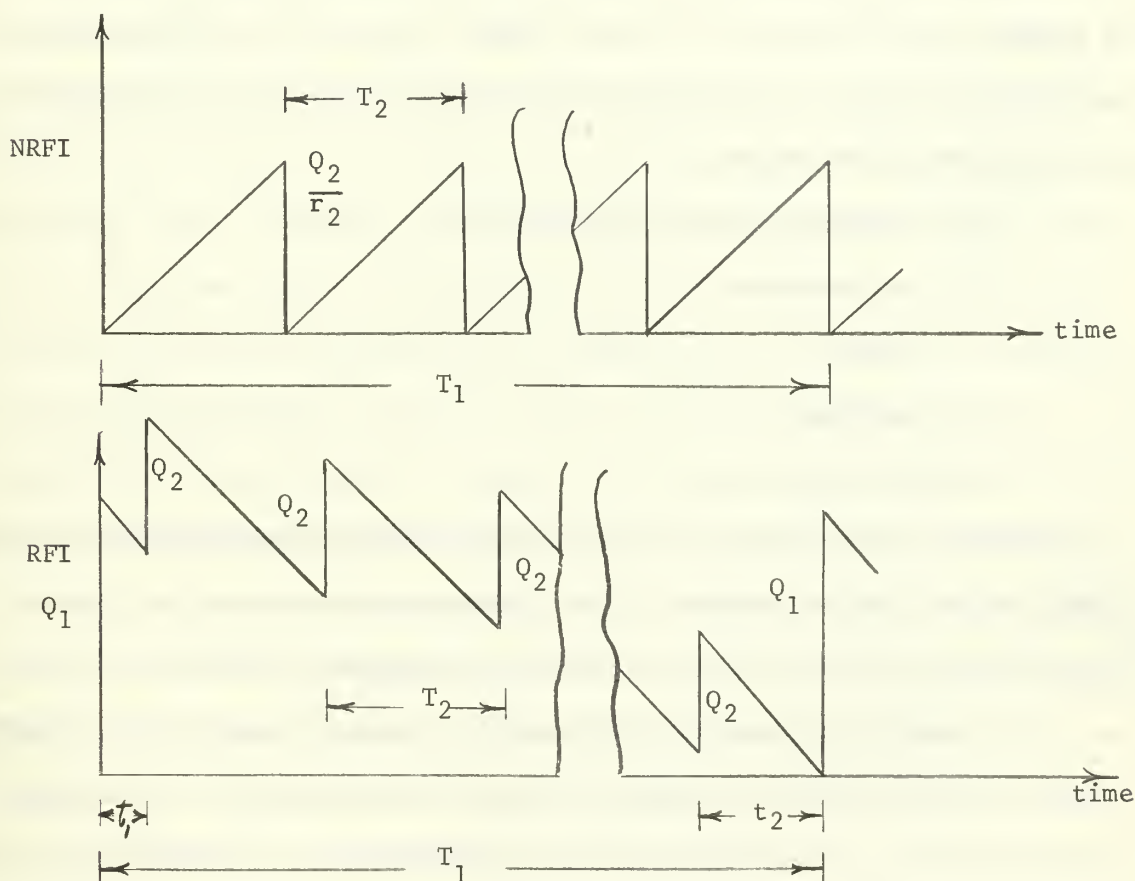


Figure 4. Procurement and Repair Cycles

Prior models designed to develop decision rules for repairable inventory systems have treated the repair and procurement decisions inde-

pendently. In some models the repairable decision rules have been cast in the framework of a consumable model with modified parameters. It is a major point of this thesis that the two problems should be treated simul-
taneously. Accordingly, the decision rule regarding "when" and "how much" to procure as well as "when" and "how much" to repair is derived by minimizing the total average annual variable cost of operating the system accounting for both repair and procurement.

3.3 Discussion of Costs

Successful management of a repairable inventory system is dependent on proper identification of relevant costs, i.e., costs which affect the operating doctrine. Five possible broad cost categories are listed below and discussed subsequently:

1. Information and Issue Systems
2. Procurement
3. Repair
4. Holding
5. Shortage

The costs associated with maintaining financial and inventory records represent the largest segment of the information system costs. Typical among these costs are: (a) data processing equipment and related personnel, (b) commodity analysts, (c) financial inventory control, (d) AUTODIN and (e) quality control. Issue system costs are primarily: (a) requisition processing, (b) warehousemen, (c) transportation and (d) disposal. It can be rationalized that these costs are a function of demand and not the operating doctrine. For this reason information and issue systems costs will not be included in defining the total annual variable cost for determining operating doctrines.

The only real procurement cost is the cost of the items ordered, frequently called the variable order cost. If there is a price break for large quantities, then this cost is a function of the quantity ordered and the unit cost. If there is no price break, as assumed in this paper, then this cost is simply the unit cost times the quantity ordered. The traditional fixed order cost involves salaries of purchase and receiving personnel, material inspectors, telephones, paper, pencils, duplicating machines, etc. It is easily seen that both the fixed and variable order cost affect the operating doctrine and will be included as a part of the cost formulation.

The usual approach to repair costs considers in detail a set-up or tooling cost.¹ Strictly speaking, repairables cannot be handled on a production line basis simply because each item may have a different "ailment". Each item must be checked and tested separately, therefore there is no fixed set-up or tooling cost. However, there is a repair cost associated with placing an induction order. Repair costs can then be divided into direct labor and material and overhead, i.e., the cost of repairing an item can be considered to be a function of direct labor and material plus some overhead cost. It follows that the fixed repair cost is really the cost of making and carrying out the decision to induct a given quantity into the repair cycle. It is assumed here that some "average" cost, C_2 , of direct labor and material per item can be found. Thus the variable cost of repair will be formulated at C_2 times the quantity inducted. Both variable and fixed repair costs will be included in the total cost formulation since they affect operating doctrine.

¹J.F. Magee, Production Planning and Inventory Control, (New York: McGraw-Hill Book Co., Inc., 1958) p. 11.

The costs associated with maintaining items in inventory include among others, obsolescence, opportunity, deterioration, breakage and normal warehousing costs. This "holding cost" is quite intangible and has proven difficult to evaluate. In the past, holding cost has been expressed as a function of unit cost (C_1) or more specifically as $h_1 = IC_1$, where I is a holding rate. The holding rate I incorporates for the main part, opportunity, obsolescence, and warehousing costs and is usually expressed as cost per unit time per monetary unit invested in inventory. However, for purposes of this model it is assumed that there exists a holding cost, h_1 , for each RFI item and a similar cost, h_2 , for a NRFI item. Both h_1 and h_2 are defined in terms of cost per unit per unit time, which for this model is measured in dollars per unit-year. Of course both holding costs affect the operating doctrine.

Finally, the shortage cost represents the cost of being unable to meet customer demands. In general, this is a very important cost, though again quite difficult to measure. By assumption of deterministic demand and lead times it is never necessary to "go short" of stock, and so shortage costs have been excluded from the model presented in this paper.

Figure 5 shows the activities at which system costs are incurred.

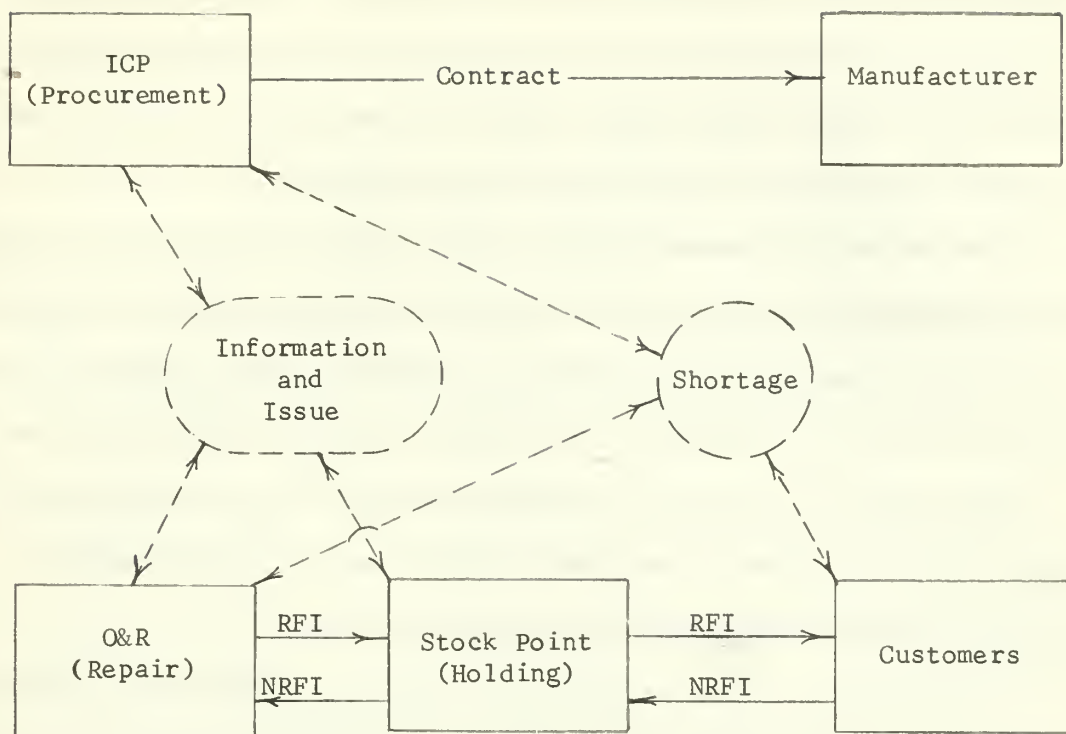


Figure 5. System Costs

4. Solutions

As previously stated the objective of the model is to determine a procurement and repair quantity that minimizes the average annual cost. These optimal values, Q_1^* and Q_2^* , coupled with respective reorder points, X_1 and X_2 , constitute an optimal operating doctrine.

To determine the average annual variable cost, the costs per cycle will be investigated. The product of per cycle costs and the number of cycles per year will yield the average annual cost. The total cost for any given cycle T_1 is the sum of procurement, repair and holding costs.

Since there is only one procurement per cycle, the variable order cost is the actual cost of the items ordered and can be expressed as $Q_1 C_1$. The fixed procurement cost for one cycle is A_1 .

To determine the repair costs per cycle it is necessary to compute the number of repair cycles per procurement cycle. Let $\frac{T_1}{T_2} = n$. It will be shown that n is an integer. It is sufficient to show that $t_1 + t_2 = T_2$ where $t_1 = kT_2$ for some $0 \leq k \leq 1$ and $t_2 = (1-k)T_2$ (cf. Figure 6). This follows because $T_1 - (t_1 + t_2)$ is an integer number of repair cycles by definition. By assumption a quantity Q_2 will arrive at intervals of length T_2 as long as there is sufficient NRFI material to induct. But also, by assumption, the arrival of a quantity Q_1 insures that there will always be enough NRFI to allow for induction. Moreover, it was assumed that a quantity Q_1 will arrive only when RFI on hand balance reaches zero and this is prior to the arrival of a scheduled repair delivery. Let the time between the arrival of a procurement and the very next repair arrival be t^* . Now, $t_2 + t^* = T_2$ since a repair quantity arrives at every interval T_2 . But $t^* = t_1$, since demand and leadtimes are deterministic, and the cycles are periodic. Thus $\frac{T_1}{T_2} = n$, where n is some positive integer.

Therefore the cost of items repaired per procurement cycle is $C_2 Q_2 n$ and the fixed repair cost is $A_2 n$, where A_2 is defined to be the fixed repair cost per induction.

In Section 3, h_1 and h_2 were defined as RFI and NRFI holding costs per unit per unit time respectively. Therefore the holding costs per cycle will be $h_1 \mathcal{A}_{T_1} + h_2 \mathcal{A}_{T_2}$, where \mathcal{A}_{T_1} is the area under the RFI curve and \mathcal{A}_{T_2} is the area under the NRFI curve. To compute the area under the RFI curve consider Figure 6 showing RFI for one procurement cycle.

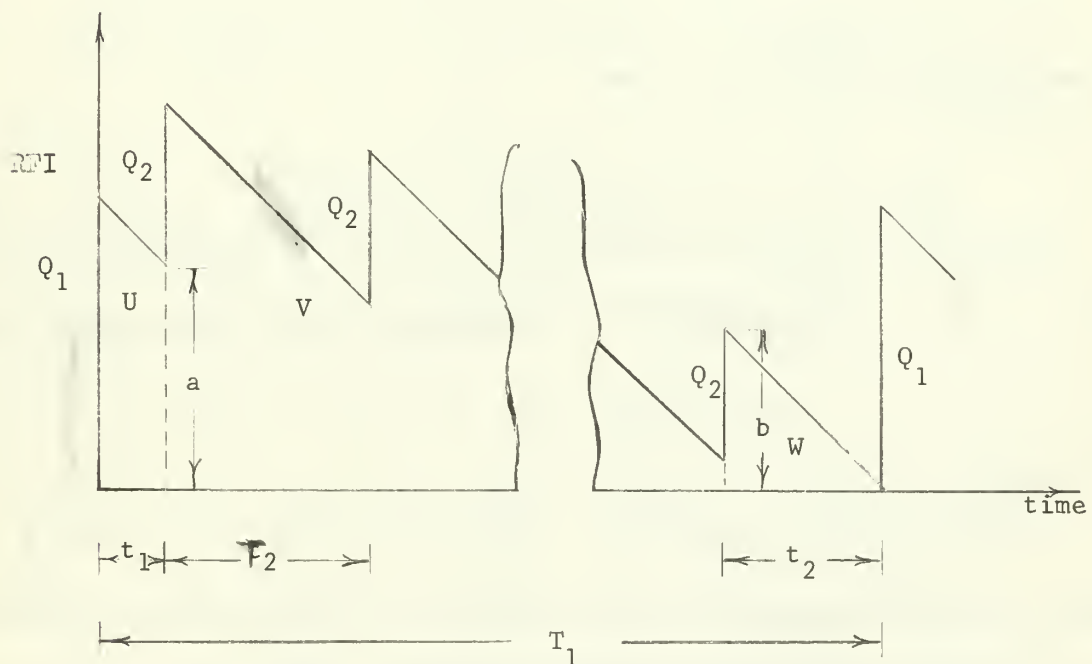


Figure 6. Procurement Cycle

Since D is known and constant, the area of U , \mathcal{A}_U , is simply $\frac{1}{2} t_1 (Q_1 + a)$, where $t_1 = kT_2$ and $a = Q_1 - Dt_1$. This reduces to

$$(4-1) \quad \mathcal{A}_U = t_1 Q_1 - \frac{Dt_1^2}{2}.$$

Since n is an integer, the area of V is the sum of $n-1$ trapezoids each

having one side of length T_2 . To determine the area of each trapezoid a recursive relation will be developed. Let \mathcal{A}_{V_i} denote the area of the i^{th} trapezoid in V (Figure 6). Then,

$$\mathcal{A}_{V_1} = \frac{1}{2}T_2 \left[2Q_2 + 2(Q_1 - t_1D) - DT_2 \right],$$

$$\mathcal{A}_{V_2} = \frac{1}{2}T_2 \left[4Q_2 + 2(Q_1 - t_1D) - 3DT_2 \right],$$

and proceeding recursively,

$$\mathcal{A}_{V_i} = \frac{1}{2}T_2 \left[2iQ_2 + 2(Q_1 - t_1D) - (2i - 1)DT_2 \right], \quad i = 1, \dots, n - 1.$$

Therefore, $\mathcal{A}_V = \sum_{i=1}^{n-1} \mathcal{A}_{V_i}$ so that

$$\begin{aligned} \mathcal{A}_V &= \frac{1}{2}T_2 \left[2Q_2 \sum_{i=1}^{n-1} i + 2(n-1)(Q_1 - t_1D) - DT_2 \sum_{i=1}^{n-1} (2i - 1) \right] \\ &= \frac{1}{2}T_2 \left[Q_2 n(n-1) + 2(n-1)Q_1 - 2(n-1)t_1D - DT_2 n(n-1) \right. \\ &\quad \left. + DT_2(n-1) \right] \end{aligned}$$

Finally,

$$(4-2) \quad \mathcal{A}_V = \frac{1}{2}T_2 \left[2(n-1)(Q_1 - t_1D) + (n^2 - n)Q_2 - (n-1)^2DT_2 \right].$$

\mathcal{A}_W is easily calculated as $\frac{1}{2}t_2b$, where $t_2 = (1 - k)T_2$ and, b from the above recursive relation of trapezoidal bases, is $nQ_2 + (Q_1 - t_1D) - (n-1)DT_2$. Thus,

$$(4-3) \quad \mathcal{A}_W = \frac{1}{2}t_2 \left[nQ_2 + Q_1 - t_1D - (n-1)DT_2 \right].$$

Finally the total area under the RFI curve is

$$\begin{aligned} \mathcal{A}_{T_1} &= \mathcal{A}_U + \mathcal{A}_V + \mathcal{A}_W = t_1Q_1 - \frac{1}{2}Dt_1^2 + \frac{1}{2}T_2 \left[2(n-1)(Q_1 - Dt_1) \right. \\ (4-4) \quad &\quad \left. + (n^2 - n)Q_2 - (n-1)^2DT_2 \right] + \frac{1}{2}t_2 \left[Q_1 - Dt_1 + nQ_2 - \right. \\ &\quad \left. (n-1)DT_2 \right]. \end{aligned}$$

To compute the area under the NRFI curve consider a single repair cycle as shown in Figure 7. Since n is an integer and the buildup rate of NRFI items, $r_0 D$, is constant, the area under the NRFI curve is simply n times the area under the repair cycle curve.

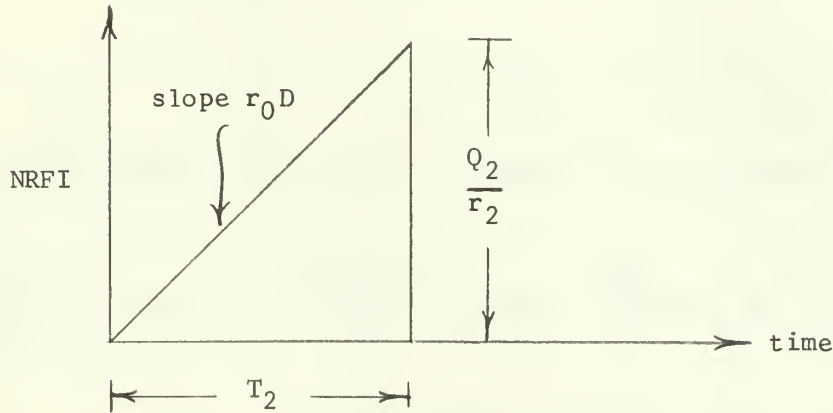


Figure 7. Repair Cycle

The area under the repair cycle curve (Figure 7) is $\frac{T_2 Q_2}{2r_2}$ so that the NRFI holding cost per procurement cycle is $\frac{nT_2 Q_2 h_2}{2r_2}$.

The total cost per procurement cycle becomes

$$(4-5) \quad \mathcal{K}_{T_1} = Q_1 C_1 + A_1 + \frac{A_2 T_1}{T_2} + \frac{C_2 Q_2 T_1}{T_2} + \frac{h_2 Q_2 T_1}{2r_2} + h_1 A_{T_1}.$$

The total average annual cost is then

$$(4-6) \quad \mathcal{K} = \frac{\mathcal{K}_{T_1}}{T_1} = \frac{Q_1 C_1}{T_1} + \frac{A_1}{T_1} + \frac{A_2}{T_2} + \frac{C_2 Q_2}{T_2} + \frac{h_2 Q_2}{2r_2} + \frac{h_1 A_{T_1}}{T_1}.$$

To simplify \mathcal{K} the following relations are helpful:

$$(1) \quad T_2 = \frac{Q_2}{r_2 r_0^D} ; \quad (2) \quad \frac{T_1}{T_2} = n, \quad n \in \{1, 2, 3, \dots\};$$

$$(3) \quad t_1 = kT_2 = \frac{kQ_2}{r_2 r_0^D} \quad \text{for } 0 \leq k \leq 1;$$

(4-7)

$$(4) \quad t_1 + t_2 = T_2; \quad (5) \quad T_1 = \frac{Q_1}{(1-r_0 r_2)^D} = \frac{Q_1}{RD} ;$$

$$(6) \quad R = (1-r_0 r_2)$$

Substituting the above relations in (4-6) and simplifying terms yields

$$(4-8) \quad \mathcal{K} = \frac{A_1 RD}{Q_1} + C_1 RD + \frac{A_2 r_2 r_0^D}{Q_2} + C_2 r_2 r_0^D + \frac{h_2 Q_2}{2r_2} \\ + \frac{h_1 Q_1}{2} - h_1 k Q_2 + \frac{h_1 Q_2}{2}$$

Note that the terms $C_1 RD$ and $C_2 r_0 r_2^D$ are independent of Q_1 and Q_2 , hence do not affect the operating doctrine. Therefore, it is appropriate to redefine the average annual cost of ordering, repairing and holding as

$$(4-9) \quad K = \frac{A_1 RD}{Q_1} + \frac{A_2 r_0 r_2^D}{Q_2} + \frac{h_2 Q_2}{2r_2} + \frac{h_1 Q_1}{2} - h_1 k Q_2 + \frac{h_1 Q_2}{2}$$

From differential calculus the optimal Q_1 and Q_2 will be those values that satisfy the equations

$$(4-10) \quad \frac{\partial K}{\partial Q_1} = 0 \quad \text{and} \quad \frac{\partial K}{\partial Q_2} = 0.$$

Since $r_2 > 0$ by assumption, and non-negative values of Q_1 , Q_2 are meaningless, K is continuous for all other values of Q_1 and Q_2 is differentiable. Taking the partial derivatives results in

$$\frac{\partial K}{\partial Q_1} = \frac{-A_1 RD}{Q_1^2} + \frac{h_1}{2} ; \quad \frac{\partial K}{\partial Q_2} = \frac{-A_2 r_0 r_2^D}{Q_2^2} + \frac{h_2}{2r_2} - kh_1 + \frac{h_1}{2}$$

Solving the equations (4-10) yields

$$(4-11) \quad Q_1^* = \sqrt{\frac{2A_1RD}{h_1}}$$

$$(4-12) \quad Q_2^* = \sqrt{\frac{2A_2r_0r_2^2D}{h_2 + r_2h_1(1-2k)}}$$

where Q_1^* and Q_2^* are the optimal procurement and repair quantities respectively. Strictly speaking, Q_1^* and Q_2^* are not optimal quantities in the sense that the restriction $\frac{T_1}{T_2} = n$, where n is a positive integer, has not been considered as a constraint in the solution. Since $T_1 = \frac{Q_1}{RD}$ and $T_2 = \frac{Q_2}{r_0r_2D}$, the equation $\frac{T_1}{T_2} = n$ is equivalent to the constraint

$$\frac{Q_1r_0r_2}{Q_2r} = n. \quad \text{In Section 5 a method will be presented for adjusting } Q_1^*$$

and/or Q_2^* such that the constraint is satisfied. In addition, a slight inaccuracy will result from round-off of Q_1^* and Q_2^* for the purpose of ordering integer quantities.

Notice that the optimal value, Q_1^* , is independent of k and in fact if $R = 1$ there is no repair, and Q_1^* is the standard EOQ formula for consumables. However, Q_2^* is a function of the parameter k , where $0 \leq k \leq 1$. Therefore, it is desirable to determine how sensitive the model is to k . By assumption, simultaneous receipt of a Q_1 and Q_2 is not possible so that $0 < k < 1$. By definition $t_1 = kT_2$. It has been shown that $t_1 + t_2 = T_2$ which implies $T_2 - t_2 = kT_2$ or

$$(4-13) \quad k = 1 - \frac{t_2}{T_2}$$

Consider the length of time t_2 . Since $t_2 < T_2$ by assumption, $t_2 < \frac{Q_2}{r_2r_0D}$.

by equation (4-7 (1)). But t_2 is at least the length of time necessary

to issue Q_2 , i.e., $\frac{Q_2}{D} \leq t_2$, and $\frac{Q_2}{D} \leq t_2 < \frac{Q_2}{r_2 r_0 D}$. From equation (4-13), when t_2 takes on its minimum value, $\frac{Q_2}{D}$,

$$k = 1 - \frac{Q_2/D}{Q_2/r_2 r_0 D} = 1 - r_2 r_0 = R.$$

As t_2 approaches $\frac{Q_2}{r_2 r_0 D}$, k approaches 0. Thus $0 < k \leq R$. Substituting

Q_1^* and Q_2^* in (4-9) gives the minimum average annual cost of the system, K^* as a function of k :

$$(4-14) \quad K^* = \frac{A_1 R D}{Q_1^*} + \frac{A_2 r_0 r_2 D}{Q_2^*} + \frac{h_2 Q_2^*}{2 r_2} + \frac{h_1 Q_1^*}{2} - h_1 k Q_2^* + \frac{h_1 Q_2^*}{2}$$

Actually (4-14) represents a family of minimum costs indexed by k where $0 < k \leq R$. To determine a k that yields a minimum in this family observe that (4-14) can be written as

$$K^* = f(Q_1^*, Q_2^*) - k h_1 Q_2^*$$

where f is not a function of k . Moreover, k is a free variable in the sense that k is not determined by Q_1^* and Q_2^* and hence the optimization procedure is independent of k . Clearly, the value of k that minimizes (4-14) is $k = R = 1 - r_0 r_2$ so that the particular solution is determined by

$$(4-15) \quad Q_2^* = \sqrt{\frac{2 A_2 r_0 r_2^2 D}{h_2 + r_2 h_1 (1 - 2R)}}$$

The repair reorder point, X_2 , is simply $\frac{Q_2}{r_2}$ (in terms of NRFI) by the original induction policy as previously discussed on page 17.

In order to determine the procurement reorder point, X_1 , first consider the case $\mathcal{T}_1 \leq T_1$. To ensure that an order arrives when on hand RFI inventory reaches zero and no repair lot is due, i.e., the end of a cycle, a procurement must be placed \mathcal{T}_1 time units prior to reaching the end of

the cycle. Since cycles are cyclic this implies that an order should be placed at time $T_1 - \mathcal{T}_1$ after the beginning of every cycle. See Figure 8.

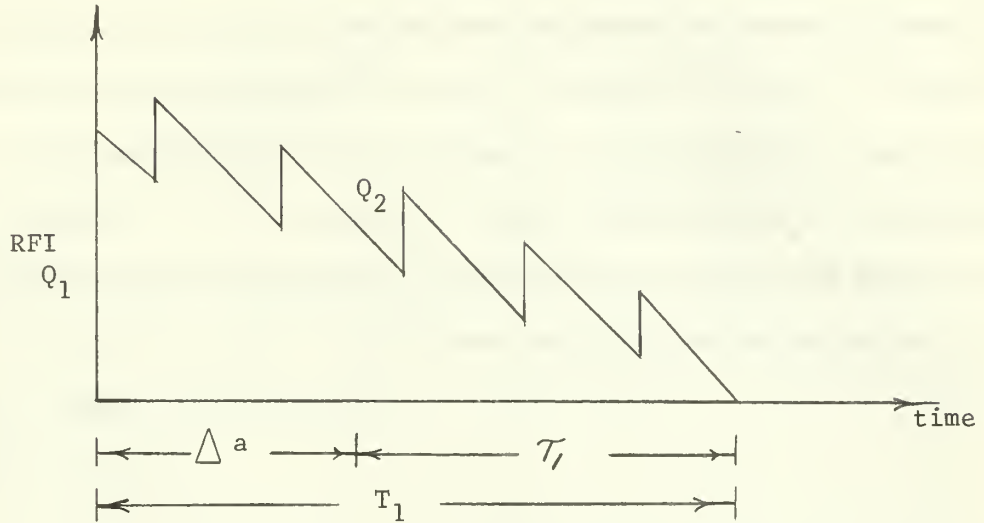


Figure 8. Procurement Reorder Point ($\mathcal{T}_1 \leq T_1$)

When $\mathcal{T}_1 > T_1$, as in Figure 9, when there is more than one cycle in a procurement leadtime.

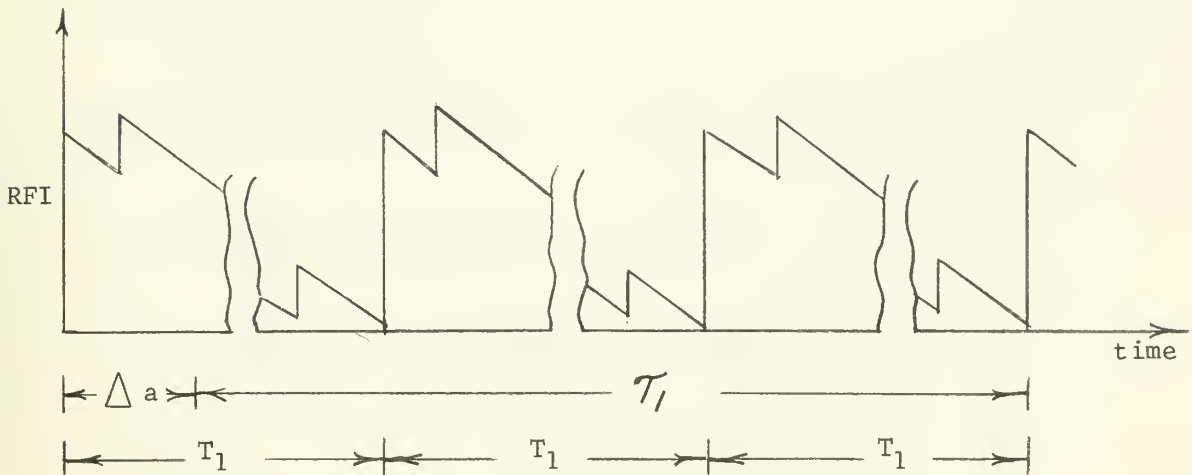


Figure 9. Procurement Reorder Point ($\mathcal{T}_1 > T_1$)

Let m be the smallest integer such that $mT_1 > \tau_1$. Define Δ_a to be the positive quantity $mT_1 - \tau_1$. Then Δ_a is the amount of time between the least number of cycles greater than τ_1 and τ_1 , and an order should be placed Δ_a units of time after the beginning of a cycle. This order will arrive τ_1 units of time later and will coincide with the end of a cycle. Note that if $\tau_1 \leq T_1$, $m = 1$, and this is the preceding case. Thus, in any case, if we define $\Delta_a = mT_1 - \tau_1$ where m is the smallest integer such that $mT_1 > \tau_1$, the reorder rule will be to place an order Δ_a units of time after the beginning of each cycle.

5. Examples

To illustrate the use of the decision rules developed in Section 4, two examples will be presented. Consider first a repairable system which carries an item experiencing relatively low demand. The item has parameters with the following values:

$$\begin{aligned}
 D &= 120 \text{ units per yr} & k = R = 1 - r_0 r_2 &= 0.0975 \\
 r_0, r_2 &= 0.95 & C_2 &= \$250.00 \text{ per unit} \\
 C_1 &= \$500.00 \text{ per unit} & A_2 &= \$50.00 \text{ per induction} \\
 A_1 &= \$100.00 \text{ per order} & h_2 &= \$50.00 \text{ per unit per yr} \\
 h_1 &= \$100.00 \text{ per unit per yr} & \tau_2 &= 0.25 \text{ yr} \\
 \tau_1 &= 1.0 \text{ yr}
 \end{aligned}$$

From (4-11) and (4-12) the unconstrained optimal order and repair quantities are:

$$\begin{aligned}
 Q_1^* &= \sqrt{\frac{2A_1 RD}{h_1}} = \sqrt{\frac{2(100)(0.0975)(120)}{100}} = 4.838 \text{ units} \\
 Q_2^* &= \sqrt{\frac{2A_2 r_0 r_2^2 D}{h_2 - 2r_2 h_1 k + h_1 r_2}} = \sqrt{\frac{2(50)(0.95)^3(120)}{50 - 2(0.95)(100)(0.0975) + 100(0.95)}} \\
 &= 9.017 \text{ units}
 \end{aligned}$$

To examine the constraint $\frac{T_1}{T_2} = n$ (a positive integer), compute

$$T_1 = \frac{Q_1^*}{RD} = \frac{4.838}{(0.0975)(120)} = 0.4135 \text{ yr}$$

$$T_2 = \frac{Q_2^*}{r_0 r_2 D} = \frac{9.017}{(0.95)^2(120)} = 0.0833 \text{ yr}$$

$$\frac{T_1}{T_2} = 4.97$$

Thus the constraint is not satisfied and to obtain a consistent policy

it is necessary to adjust T_1 or T_2 to make $\frac{T_1}{T_2} = n$, a positive integer.

It is reasonable to select the integer nearest 4.97, i.e., choose $n = 5$.

Adjusting T_1 will yield the following values:

$$Q_1^*(\text{adj}) = 4.873 ; \quad Q_2^* = 9.017$$

$$T_1(\text{adj}) = 0.4165; \quad T_2 = 0.0833$$

To check the new solution we obtain

$$\frac{T_1}{T_2} = \frac{Q_1 r_2 r_0}{Q_2 R} = \frac{4.873(0.9025)}{9.017(0.0975)} = 5.0026 \approx 5$$

Thus the policy is consistent with the model of Section 4. However, an operating system cannot deal with fractional units so $Q_1^*(\text{adj})$ and Q_2^* must be rounded off to 5 and 9 units respectively. This results in further interval computations as follows:

$$T_1 = 0.427 \text{ yr}; \quad T_2 = 0.0831 \text{ yr}; \quad \frac{T_1}{T_2} = 5.14$$

But in this case the system will be out of stock after five repair cycles, i.e., for a period $(.14)T_2 = .0116$ year. To compensate for this period so as not to allow shortages, the reorder point must be adjusted. Recall from Section 4 that the rule is to reorder $\Delta_a = mT_1 - \tau_1$ units of time after the beginning of each cycle. To ensure a procurement arrival at the point a zero balance is reached, an order for a quantity $Q_1 = 5$ must be placed $\Delta_a - .14T_2$ time units after the commencement of a procurement cycle. Since $\tau_1 = 1$ year, $m = 3$, $\Delta_a = .281$ year, and $\Delta_a - .14T_2 = .2694$ year. Thus a workable policy is to procure 5 units .2694 year after the beginning of each procurement cycle. The repair quantity is $Q_2 = 9$ units.

Substituting the appropriate values from all three sets of computations in

$$K^* = \frac{A_1 R D}{Q_1^*} + \frac{A_2 r_0 r_2 D}{Q_2^*} + \frac{h_2 Q_2^*}{2r_2} + \frac{h_1 Q_1^*}{2} - h_1 k Q_2^* + \frac{h_1 Q_2^*}{2}$$

results in three cost comparisons as follows:

$$\begin{aligned} K^*(Q_1 = 4.838, Q_2 = 9.017) &= 241.84 + 600.53 + 237.33 + 241.90 \\ &\quad - 87.92 + 450.85 = \underline{\$1684.53} \\ K^*_{(\text{adj})}(Q_1 = 4.873, Q_2 = 9.017) &= 240.10 + 600.53 + 237.33 + 243.65 \\ &\quad - 87.92 + 450.85 = \underline{\$1684.54} \\ K^*_{(\text{round off})}(Q_1 = 5, Q_2 = 9) &= 234.00 + 601.67 + 236.88 + 250.00 \\ &\quad - 87.75 + 450.00 = \underline{\$1684.80} \end{aligned}$$

As a second example consider a system carrying a repairable item with the following parameters:

$$\begin{aligned} D &= 12,000 \text{ units per yr} & k &= R = 1 - r_0 r_2 = 0.19 \\ r_0, r_2 &= 0.90 & C_2 &= \$50.00 \text{ per unit} \\ C_1 &= \$100.00 \text{ per unit} & A_2 &= \$50.00 \text{ per induction} \\ A_1 &= \$50.00 \text{ per order} & h_2 &= \$10.00 \text{ per unit per yr} \\ h_1 &= \$20.00 \text{ per unit per yr} & T_2 &= 0.25 \text{ yr} \\ T_1 &= 0.75 \text{ yr} \end{aligned}$$

The results of the computations are indicated in Table 1.

| | 1st Computation | Q_1 Recomputed | Q_1, Q_2 rounded-off |
|---------|-----------------|------------------|------------------------|
| Q_1^* | 106.77 | 95.30 | 95 |
| Q_2^* | 203.33 | 203.33 | 203 |
| T_1 | 0.0468 | 0.0418 | 0.0417 |
| T_2 | 0.0209 | 0.0209 | 0.0209 |
| n | 2.239 | 2 | 1.995 |
| K^* | \$6,914.75 | \$6,928.55 | \$6,929.33 |

Table 1

Results of Order and Repair Quantity Calculations

6. Constraints

In general, it is very unlikely that an inventory system would be established to manage a single line item. In applying the theory developed in Section 4 it becomes apparent that consideration must be given to inventory systems that manage many line items. In a multi-item inventory there can be many types of interactions between items. Notable among these are the interactions of items competing for limited resources. For example, there would most likely be an upper limit to the number of repair inductions directed per year. There most assuredly is a limit on funds that can be used for procurement of new items. These limits are called constraints. The remainder of this section will investigate the effect that certain constraints have on the repairable model. The constraints to be considered are; (a) number of procurements per year, (b) number of repair inductions per year, (c) dollar investment in inventory and (d) annual repair budget, i.e., repair dollars that can be spent for direct labor and materials.

Consider first the constraint on the number of procurements per year, P. Assume there are M items in the inventory system and let j denote the j^{th} item. The constraint can then be expressed as

$$(6-1) \quad \sum_{j=1}^M \frac{D_j}{Q_{1j}} \leq P$$

since quantity Q_{1j} is ordered each time an order is placed. Let K_1 be those terms of equation (4-9) involving the variables in the constraint. Thus, if

$$(6-2) \quad K_{1j} = \frac{A_{1j} R_j D_j}{Q_{1j}} + \frac{h_{1j} Q_{1j}}{2}, \quad j = 1, \dots, M$$

is that portion of the cost of the j^{th} item that is affected by the

quantity procured, then the cost for the system is

$$(6-3) \quad K_1 = \sum_{j=1}^M K_{1j}$$

To find the optimal Q_{1j} , $j = 1, \dots, M$, it is desirable to minimize K_1 subject to equation (6-1). The reader is referred to Hadley and Whitin (2) for the necessary mathematical background needed to solve problems of this type. Briefly, the procedure is to first solve the unconstrained problem by using equation (4-11) for each item. Then substitute these Q_{1j} into equation (6-1). If (6-1) is satisfied the constraint is said to be inactive and the problem is solved. Assuming the constraint is active, i.e., quantities computed by using equation (4-11) do not satisfy equation (6-1), the technique of Lagrange multipliers is employed to determine optimal order quantities. Form the function

$$(6-4) \quad J_1 = K_1 + \lambda_1 \left(\sum_{j=1}^M \frac{D_j}{Q_{1j}} - P \right)$$

where λ_1 is a Lagrange multiplier. The optimal Q_{1j} must satisfy the equations

$$(6-5) \quad \frac{\partial J_1}{\partial Q_{1j}} = 0 = \frac{-A_{1j} R_j D_j}{Q_{1j}^2} + \frac{h_{1j}}{2} - \frac{\lambda_1 D_j}{Q_{1j}^2}, \quad j = 1, \dots, M$$

$$(6-6) \quad \frac{\partial J_1}{\partial \lambda_1} = 0 = \sum_{j=1}^M \frac{D_j}{Q_{1j}} - P$$

A solution to the set of $M+1$ equations in (6-5) and (6-6) may not exist in closed form. In this case, a numerical procedure should be used to approximate the optimal Q_{1j} . In any case, solving for Q_{1j} in equation (6-5) yields

$$(6-7) \quad Q_{1j}^* = \sqrt{\frac{2D_j}{h_{1j}} (A_{1j}R_j + \lambda_1^*)}, \quad j = 1, \dots, M$$

where λ_1^* is that value of λ_1 such that the Q_{1j}^* , $j = 1, \dots, M$, satisfy

$$(6-8) \quad P = \sum_{j=1}^M \frac{D_j}{Q_{1j}^*} = \sum_{j=1}^M \sqrt{\frac{D_j h_{1j}}{2(A_{1j}R_j + \lambda_1^*)}}$$

Clearly, λ_1^* can not be expressed in closed form without making further assumptions so that a numerical procedure must be used to solve for the Q_{1j}^* .

Consider next the constraint on the number of repair inductions per year, L . This constraint can be expressed as

$$(6-9) \quad \sum_{j=1}^M \frac{r_{2j}r_{0j}D_j}{Q_{2j}} \leq L$$

Let K_2 be those terms of K involving the variables in the constraint.

Thus, if

$$(6-10) \quad K_{2j} = \frac{A_{2j}r_{2j}r_{0j}D_j}{Q_{2j}} + \frac{h_{2j}Q_{2j}}{2r_{2j}} - h_{1j}k_j Q_{2j} + \frac{h_{1j}Q_{2j}}{2},$$

$j = 1, \dots, M$

is that portion of the cost of the j^{th} item that is affected by the quantity inducted for repair, then the system cost is

$$(6-11) \quad K_2 = \sum_{j=1}^M K_{2j}$$

To determine the set of Q_{2j} which minimize K_2 subject to equation (6-9) the function

$$(6-12) \quad J_2 = K_2 + \lambda_2 \left(\sum_{j=1}^M \frac{r_{0j}r_{2j}D_j}{Q_{2j}} - L \right)$$

is formed where λ_2 is the Lagrange multiplier. The optimal Q_{2j} must satisfy the equations

$$(6-13) \quad \frac{\partial J_2}{\partial Q_{2j}} = 0 = \frac{-A_{2j}r_{0j}r_{2j}^D}{Q_{2j}^2} + \frac{h_{2j}}{2r_{2j}} - \frac{h_{1j}}{2} - h_{1j}^k - \frac{\lambda_2 r_{0j}r_{2j}^D}{Q_{2j}^2}, \quad j = 1, \dots, M$$

$$(6-14) \quad \frac{\partial J_2}{\partial \lambda_2} = 0 = \sum_{j=1}^M \frac{r_{2j}r_{0j}^D}{Q_{2j}} - L$$

Solution of equation 6-13) yields

$$(6-15) \quad Q_{2j}^* = \sqrt{\frac{r_{2j}r_{0j}^D(A_{2j} + \lambda_2^*)}{\frac{h_{2j}}{2r_{2j}} + \frac{h_{1j}}{2} - h_{1j}^k}}, \quad j = 1, \dots, M$$

where λ_2^* is that value of λ_2 such that the Q_{2j}^* satisfy

$$(6-16) \quad L = \sum_{j=1}^M \frac{r_{2j}r_{0j}^D}{Q_{2j}^*} = \sum_{j=1}^M \sqrt{\frac{r_{2j}r_{0j}^D(\frac{h_{2j}}{2r_{2j}} + \frac{h_{1j}}{2} - h_{1j}^k)}{A_{2j} + \lambda_2^*}}$$

Notice the assumption that $A_{21} = A_{22} = A_{23}$ yields a solution of λ_2^* in equation (6-16), and thus Q_{2j}^* in equation (6-15), by elementary methods. Practically speaking, this assumption is very reasonable since it is unlikely that the cost of making a repair induction would depend on the item.

Consider next the constraint on dollar inventory investment, I_1 . This requires that

$$(6-17) \quad \sum_{j=1}^M C_{1j}Q_{1j} \leq I_1$$

Letting K_3 be the terms of K involving the variables in the constraint,

it is seen that $K_{3j} = K_{1j}$ and $K_3 = \sum_{j=1}^M K_{3j} = K_1$. Define the function

$$(6-18) \quad J_3 = K_3 + \lambda_3 \left(\sum_{j=1}^M C_{1j} Q_{1j} - I_1 \right)$$

where λ_3 is the Lagrange multiplier. The optimal Q_{1j} must then satisfy the equations

$$(6-19) \quad \frac{\partial J_3}{\partial Q_{1j}} = 0 = \frac{-A_{1j} R_j D_j}{Q_{1j}^2} + \frac{h_{1j}}{2} + \lambda_3 C_{1j}, \quad j = 1, \dots, M$$

$$(6-20) \quad \frac{\partial J_3}{\partial \lambda_3} = 0 = \sum_{j=1}^M C_{1j} Q_{1j} - I_1$$

Solution of equation (6-19) yields

$$(6-21) \quad Q_{1j}^* = \sqrt{\frac{A_{1j} R_j D_j}{\frac{h_{1j}}{2} + \lambda_3^* C_{1j}}}, \quad j = 1, \dots, M$$

where λ_3^* is that value of λ_3 such that the Q_{1j}^* satisfy

$$(6-22) \quad I_1 = \sum_{j=1}^M C_{1j} \sqrt{\frac{A_{1j} R_j D_j}{\frac{h_{1j}}{2} + \lambda_3^* C_{1j}}}$$

Finally, consider the constraint on the annual repair budget, I_2 .

This constraint is expressed as

$$(6-23) \quad \sum_{j=1}^M C_{2j} Q_{2j} \leq I_2$$

If K_4 represents the terms of K involving the variables in the constraint, it is seen that $K_{4j} = K_{2j}$ and $K_4 = \sum_{j=1}^M K_{4j} = K_2$. To determine the optimal Q_{2j} subject to (6-23), the function

$$(6-24) \quad J_4 = K_4 + \lambda_4 \left(\sum_{j=1}^M C_{2j} Q_{2j} - I_2 \right)$$

is formed where λ_4 is the Lagrange multiplier. It follows that the optimal Q_{2j} must satisfy the equations

$$(6-25) \quad \frac{\partial J_4}{\partial Q_{2j}} = 0 = \frac{-A_{2j} r_{2j} r_{0j} D_j}{Q_{2j}^2} + \frac{h_{2j}}{2r_{2j}} + \frac{h_{1j}}{2} - h_{1j} k_j + \lambda_4 C_{2j}, \quad j = 1, \dots, M$$

$$(6-26) \quad \frac{\partial J_4}{\partial \lambda_4} = 0 = \sum_{j=1}^M C_{2j} Q_{2j} - I_2$$

Solution of (6-25) yields

$$(6-27) \quad Q_{2j}^* = \sqrt{\frac{A_{2j} r_{2j} r_{0j} D_j}{\frac{h_{2j}}{2r_{2j}} + \frac{h_{1j}}{2} - h_{1j} k_j + \lambda_4^* C_{2j}}}, \quad j = 1, \dots, M$$

where λ_4^* is that value of λ_4 such that the Q_{2j}^* satisfy

$$(6-28) \quad I_2 = \sum_{j=1}^M C_{2j} \sqrt{\frac{A_{2j} r_{2j} r_{0j} D_j}{\frac{h_{2j}}{2r_{2j}} + \frac{h_{1j}}{2} - h_{1j} k_j + \lambda_4^* C_{2j}}}$$

The following example illustrates the employment of a single constraint. Consider a repairable inventory system of the type presented here which stocks three items, i.e., $M = 3$. The management wishes to restrict the number of repair inductions per year to 50, thus $L \leq 50$. It can be rationalized that the fixed repair cost, A_{2j} , is the same for all items thus it will be assumed here that $A_{21} = A_{22} = A_{23} = \50.00 . The remainder of the pertinent data is listed in Table 2.

| Item | 1 | 2 | 3 |
|----------------------------|--------|-------|---------|
| Field recovery rate, r_0 | 0.95 | 0.90 | 0.95 |
| O&R recovery rate, r_2 | 0.95 | 0.90 | 0.95 |
| Demand rate, D | 240 | 2,000 | 200 |
| NRFI holding cost, h_2 | \$60 | \$10 | \$100 |
| RFI holding cost, h_1 | \$120 | \$20 | \$200 |
| Cycle constant, k | 0.0975 | 0.19 | 0.0975 |
| Unit cost, C_1 | \$600 | \$100 | \$1,000 |
| Unit repair cost, C_2 | \$300 | \$60 | \$700 |

Table 2. Parameter Values for a Three Item Inventory System

Without the constraint, $L \leq 50$, the optimal repair quantities are given by equation (4-12). Computing we get $Q_{21}^* = 11.64$, $Q_{22}^* = 83.01$ and $Q_{23}^* = 8.23$. With these values of Q_{2j} , the number of repair inductions per year would be 60.04. Thus the constraint is active and equations (6-15) and (6-16) are used to compute the Q_{2j} . Under the assumption $A_{21} = A_{22} = A_{23}$, equation (6-16) yields $\lambda_2^* = 21.98$. Substituting this value in equation (6-15) gives $Q_{21}^* = 13.97$, $Q_{22}^* = 99.84$ and $Q_{23}^* = 9.88$. As expected, constraining the number of repair inductions increases the size of the repair quantities for each item.

It is interesting to see how the constraint affects system operating cost. Consider only that portion of the total cost that is affected by the repair quantity, as given by equation (6-11). The unconstrained Q_{2j}^* , i.e., $L = 60.04$, yields $K_2 = \$6004.08$. For $L = 50$, $K_2 = \$6104.90$. Thus the constraint forces the system operating cost to exceed the optimal cost by \$100.82.

It is quite possible that more than one constraint could be imposed at one time. For example, suppose that all four of the constraints previously considered separately are now imposed simultaneously. It is desired to minimize system variable cost subject to (6-1), (6-9), (6-17) and (6-24). Denote system variable cost by K . It is seen that

$$(6-29) \quad K = K_1 + K_2$$

To minimize K the following procedure is used: First solve the unconstrained problem to find Q_{1j} and Q_{2j} for $j=1, \dots, M$, by using (4-12). With these values check to see if any of the four constraints are active. If all constraints are inactive, the problem is solved. If one or more constraints are active, use the method of Lagrange multipliers, as described in this section, to find new values for Q_{1j} and Q_{2j} . Again the constraints are checked to determine if they are active. The process is repeated for each constraint as long as any constraint is active. When all four constraints have been used singly, two constraints are tested at a time by employing two Lagrange multipliers. Again the remaining constraints are checked to see if they are active. If either constraint is active, another set of two constraints is used employing two Lagrange multipliers to find new values of Q_{1j} and Q_{2j} . This process is repeated until all possible combinations of two constraints are used or until solutions result for which no constraint is active. If solutions cannot be found by using two Lagrange multipliers, then the technique is extended to three multipliers and finally four. In the case where all four constraints are active under the aforementioned conditions, form the function

$$(6-30) \quad J = K + \lambda_1 \left(\sum_{j=1}^M \frac{D_j}{Q_{1j}} - P \right) + \lambda_2 \left(\sum_{j=1}^M \frac{r_{2j} r_{0j} D_j}{Q_{2j}} - L \right) \\ + \lambda_3 \left(\sum_{j=1}^M C_{1j} Q_{1j} - I_1 \right) + \lambda_4 \left(\sum_{j=1}^M C_{2j} Q_{2j} - I_2 \right)$$

where λ_i , $i = 1, \dots, 4$, are the Lagrange multipliers. It follows that the optimal Q_{1j} and Q_{2j} must satisfy the equations

$$(6-31) \quad \frac{\partial J}{\partial Q_{1j}} = 0, j = 1, \dots, M; \quad \frac{\partial J}{\partial Q_{2j}} = 0, j = 1, \dots, M$$

$$(6-32) \quad \frac{\partial J}{\partial \lambda_i} = 0, i = 1, \dots, 4.$$

It should be mentioned that generally equations (6-31) and (6-32) will be extremely difficult to solve. In fact, in most cases it will be necessary to resort to numerical procedures that give approximations to the optimal Q_{1j} and Q_{2j} .

7. Conclusions and Acknowledgements

This thesis has formulated a decision rule for a repairable item inventory system by considering the procurement and repair decisions simultaneously. For this deterministic model, equations (4-11) and (4-12) show the optimal procurement and repair quantities to be independent. In addition, this model is suitable for a consumable item inventory system where $r_0 = r_2 = 0$.

Although the formulation of a cost equation was essential in deriving optimal operating doctrine, costs per se were not discussed in detail. To actually use this model holding cost relationships must be given. In addition the fixed costs of procurement and repair (A_1 and A_2) must be known. Although the main interest of this thesis is not in the area of costs, it is evident that further research in this area would be desirable prior to application of the model.

It should be remembered that this model considered a single item and when applied to a multi-item inventory system will result in trade-offs between items and costs. These interactions between items lead to competition among items for limited resources expressed in this model as constraints. As illustrated in Section 6, one constraint considering just a few items presented difficulties in calculations. A feasible method for handling constraints in a multi-item system must be developed.

In conclusion, it is recognized that although the thesis presents a deterministic repairable system, it is a suitable basis for future efforts in the development of models which more closely approximate operating repairable systems. In particular, an area for further research would be to consider the present model with random demand and possible random lead times as well.

The writers wish to express their sincere appreciation to Professors Peter W. Zehna and David A. Schrady for their excellent and helpful comments and suggestions during the preparation of this thesis. Their continual interest in the area of inventory control will greatly benefit future Supply Corps students.

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| | | 2b. GROUP | |
| 3. REPORT TITLE A REPAIRABLE ITEM INVENTORY MODEL | | | |
| 4. DESCRIPTIVE NOTES (Type of report and inclusive dates) Thesis, M.S., October 1966 | | | |
| 5. AUTHOR(S) (Last name, first name, initial) MCNALL, Phillip Freeman HATCHETT, John Wayne | | | |
| 6. REPORT DATE October 1966 | 7a. TOTAL NO. OF PAGES 49 | 7b. NO. OF REFS 4 | |
| 8a. CONTRACT OR GRANT NO. | 9a. ORIGINATOR'S REPORT NUMBER(S) | | |
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